

Developing Curricula for Artificial Intelligence and Robotics (DeCAIR) 618535-EPP-1-2020-1-JO-EPPKA2-CBHE-JP



DeCAIR Course Syllabus Form

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WP Number & Title	Work Package 5: Improving Existing M.Sc. Programs in Jordan and Lebanon by Implementing or Including AI and Robotics Courses			
Activity Number & Title	Task 5.1: Developing syllabi and content for added/modified courses in existing master programs in universities of partner countries			
WP Leader	Peter Eberhard, University of Stuttgart			
Due Date of Delivery	1/2/2022	Project Month	M14	
Submission Date	1/7/2021	Project Month	M7	

Revision History

Version	Date	Author	Description	Action *	Page(s)
1	1/8/2021	Clovis Francis	MSC RSI Update Course Syllabus	С	1-6
2	22/10/2021	Clovis Francis	Second version		
3					
4					

(*) Action: C = Creation, I = Insert, U = Update, R = Replace, D = Delete

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This project has been co-funded by the Erasmus+ Programme of the European Union.

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Course title	Optimization				
Course number	RSI01				
Credit hours (lecture and lab)	24 cor	24 contact hours			
ECTS (weekly contact and self-study load)	4	4			
Prerequisites/co-requisites	Opera	tions research			
Prerequisites by topic	Students are assumed to have good background in mathematics and operations research, particularly, calculus, linear algebra, statistics, and probability. Additionally, the students should have good programming skills, preferably, using Matlab Simulink, Python and Javascript.				
Level and type (compulsory, elective)	Masters' compulsory course				
Year of study and semester	Year 2	, first semester			
Description Objectives	After having presented the fundamental notions and tools for solving the optimization problem, this course presents the concepts of the deterministic, stochastic and robust optimization techniques as well as optimization under constraints formalism.				
Objectives	 Introduce students to the techniques and tools used in optimization. Introduce students to the different optimization approaches and formalisms: deterministic, stochastic and robust optimization techniques as well as constraint optimization. 				
Intended learning outcomes	Upon successful completion of this course, students will be able to:				
	No	Intended learning Outcome (ILO)	Program learning outcome (PLO)*		
	1	Demonstrate a sound understanding of the main areas of AIR.	1		
	2	Solve an AIR problem by developing an appropriate optimization approach.	3		
	3	Communicate the development of an optimization problem through a detailed technical report and a short presentation.	4,5		
	4	Use Matlab, Python and Javascript libraries to develop programs for solving optimization problems. (*) The PLOs are listed in the appendix	3		
Teaching and learning methods	Development of ILOs is promoted through the following teaching and learning methods:				

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	1				
Learning material	re Th so Th dis Th dis Th dis Th th Th Th Th Th Th th th th th th th th th th t	ectures will be delivered through Microsoft corded for later access. The AI Lab is open for the students to practice off the programming homework assignment the student attends the class presentations a scussions. The student joins the related online team/group scussions. The student studies the reference material, in the student solves the programming assignment the student carries out a term project for solve optimization techniques. The student develops a professional report for the student presents the term project in class class handouts, some instructor keynotes, so a personal computer and the internet.	e the prac nts. nd partic oup and p ncluding t ents ving a pro or the tern s.	ctical a ipates articip books a oblem u m repo	spects and in the ates in its and videos. using ort.
	1. 2. 3. 4.	Lecture notes prepared by the Instructor Numerical Optimization, Jorge Nocedal, S Numerical Optimization, Theoretical and JF., Gilbert, J.C., Lemarechal, C., Sagastiz Metaheuristic Optimization: Nature-Inspi Computational Intelligence, Theory and A Modestus, Tartibu Lagouge.	Practical ábal, Spr red Algor	Aspect inger ithms	s. Bonnans, Swarm and
Topic outline and schedule					
	Lecture	Торіс	Hours	ILO	Resources
	1	Introduction and Motivation: Engineering applications of Optimization	2	1	1,2,3, 4
	2	Non Linear optimization: Optimization Models	2	2,3 , 4	1,2,3
	3	Non-linear analytical optimization: Optimality conditions Convex Optimization, Unconstrained problems	2	2,3 , 4	1,2,3
	4	Non-linear analytical optimization: Numerical search, Equality, Inequality	2	2,3 , 4	1,2,3
	5	Non Linear Optimization: Duality	2	2,3 , 4	1,2,3
	6	Unconstrained Optimization methods: Direct, random search methods	2	2,3 , 4	1,2,3
	7	Unconstrained Optimization methods: 1 Descent method, Line search, Gradient	2	2,3 , 4	1,2,3

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		descent method, Steepest descent						
	method, Newton's method, Conjugate							
		gradient method, Q	uasi-New	/ton's				
		methods						
	8 Meta-heuristi		nods: Sim	ulated	2	2,3	1,4	
		Annealing, Particle S	Swarm O	ptimization		, 4		
	9	Meta-heuristic met	nods: Art	ificial Bee		2,3	1,4	
		Colony Algorithm, A	nt Colon	у		, 4		
	10	Genetic Algorithms			2	2,3	1,4	
						, 4		
	11	Software for optimi	zation: M	latLab	2	5	1	
		Optimization toolbo						
	12	Various applications		sand	2	5	1	
		drones path plannir			-	Ũ	-	
		diones patri planni	ig optimi	Lucion.				
Evaluation tools	ion tools Opportunities to demonstrate achievement of the ILOs are provided thro following assessment tools:				nrough the			
	Δ	ssessment tool	Mark	Т	opic(s)		Time	
		oject report,	100%		,	se of	W14	
			10070	Programming and use of optimization toolboxes for		***		
	programs and presentation			engineering problem				
				solving				
	Total		100%				<u>+</u>	
	Total		100%					
Student requirements	The stude	ent should have a com	puter and	d internet cor	nection			
-								
Course policies	A- Attend	lance policies:						
	• Attendance is required. Class attendance will be taken every class and th					ass and the		
		niversity polices will b						
				-				
	B- Absend	ces from exams and su	Ibmitting	assignments	on time	:		
	 A makeup exam can be arranged for students with acceptable absence causes. Assignments submitted late, but before announcing or discussing the solution can be accepted with 25% penalty. The project report must be handed in in time. C- Health and safety procedures: All health and safety procedures of the university and the school should be followed. D- Honesty policy regarding cheating, plagiarism, misbehavior: Open-book exams 					absence		
						ing the		
						ol should be		
	 All submitted work must be of the submitting student. 							
	• A	ii submitted work mus	st be of th	ne submitting	student			

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	 Other text or code must be properly quoted with clear source specification. Cheating will not be tolerated.
	E- Available university services that support achievement in the course:
	 Microsoft Teams team Control Lab for practicing the practical aspects and solving the programming assignments.
Additional information	None

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Appendix

Learning Outcomes for the MSc in Artificial Intelligence and Robotics

Students who successfully complete the MSc in Artificial Intelligence and Robotics (AIR) will be able to:

- 1. Demonstrate a sound understanding of the main areas of AIR including artificial neural networks, machine learning, data science, industrial and service robots, and intelligent and autonomous robots.
- 2. Apply a critical understanding of essential concepts, principles and practices of AIR, and critically evaluate tools, techniques and results using structured arguments based on subject knowledge.
- 3. Apply the methods and techniques of the AIR fields in the design, analysis and deployment of AIR solutions and solving practical problems.
- 4. Demonstrate the ability to produce a substantial piece of research work from problem inception to implementation, documentation and presentation.
- 5. Demonstrate life-long learning, independent self-learning and continuous professional development skills in the AIR fields.
- 6. Demonstrate a sound understanding of the ethical, safety and social impact issues of AIR solutions and products.

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